

CONTROL HUB

GETTING STARTED GUIDE

Control Hub Getting Started

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1 CONTROL HUB OVERVIEW

The REV Robotics Control Hub is an affordable all in one education robotics control providing the interfaces required for building robots and other mechatronics. The Control Hub is purposed built to stand up to the rigors of the classroom and competition field. It features an Android operating system and a mature software packaged designed for basic and advanced use cases with the ability to be field upgraded in the future.

The Control Hub is the approved device for use in *FIRST* Global and limited regions for *FIRST* Tech Challenge.

1.1 FEATURES

- Physical Dimensions
 - 143mm X 103mm X 29.5 mm
 - \circ Mounting holes on a 16mm spacing
- Input Voltage:
 - 12V Nominal (8-15VDC)
- Processors
 - RK3328 Quad-core ARM® Cortex-A53
 - Texas Instruments ARM® Cortex-M4
- 3.3V Ports
 - 8x Digital I/O: 1A Source Max
 - 4x I2C 100kHz/400kHz Busses: 500mA Max
 - 4x 12-bit Analog Inputs: 500mA Max
 - **4x Quadrature Encoder Inputs**: 500mA Max
- 5V Ports
 - **5V Aux Power:** 2A Max
 - o Servos: 2A Maximum per Pair
 - o USB 2.0: 1.5A Max



2QUICK START

2.1 REQUIRED MATERIALS



Optional Additional Materials needed to Connect the Expansion Hub:

- Expansion Hub (REV-31-1153)
- XT30 Extension Cable
- Communication Cable (RS-485)

2.2 DRIVER STATION AND CONTROL HUB PAIRING

When you first receive your kit, you will have to pair (link) your Driver Station (Android Device) to your Control Hub. This procedure only needs to be performed once for each set of hardware. If you exchange (replace) your Driver Station or Control Hub, this procedure will need to be repeated.



4. Open the Driver Station application from the HOME Screen.





5. On the Driver Station page, open the menu from the top right corner, then select "Settings".





10. Select the name of the Wifi network that matches the name of the network printed on your control hub. This should start with "FIRST-".		Wi-Fi On FIRST-aE1y HP-Print-EF-Lase	* • • • • • 3% 10:20 • • • • • • • • • • • • • • • • • • •
 Enter the password to the Wifi network in the password field. This defaults to "password". Press "CONNECT". After pressing connect, press the back arrow at the bottom of the display until you return to the main driver station screen. 	■ ■ ■ 1 q a ℃ ?123	FIRST-aE1y Password Show password Advanced options KEV_DO-2 2 3 4 5 W e r t s d f g z x c v ,	* ● N 3% 10:20 • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • •



2.3 CONFIGURE YOUR ROBOT

When you build your robot, you will need to configure it before you can program it. This will allow you to give your sensors and actuators meaningful names that you can reference while programming.

For this example we will use the Mini-Bot (REV-45-1171)



Configureing Your Robot for the First Time

Moto E (4)_3b31

 Select the menu on the Driver Station page. Then select "Configure Robot".





	the top left corner of the page)	3 times.
tive Configuration:	(unsaved) «No Config Set»	
Dore	Active Configuration:	(unsaved) +No Config Set+
Port Attached	Done C	
REV Robotics Core Hex Motor	Expansion Hub 1	
left_drive	Motors	Artise Conferentia-
Motor name	Servos	Dove
REV Robotics Core Hex Motor 👻	Digital Devices	Expansion Hub Portal 1
right_drive Motor name	PWM Devices	(embedded)
2 Nothing •	Analog Input Devices	Expansion Hu0 1
NO DEVICE ATTACHED	12C Bus 0	
Notor name	12C Bus 1	
3 Nothing •	I2C Bus 2	
NO DEVICE ATTACHED	12C Bus 3	
Enter "miniBot" as your configuration name, then se "OK".	elect	in configuration: in Hub Portal 1 onfiguration inter a name for the robot configuration. Cancel
	Active Configura	ition: 📩 minBot

Control Hub Getting Started

2.4 CONNECT AN EXPANSION HUB

If you want to use more than 4 motors or 6 servos, you will need to add the expansion hub to your robot. The Expansion Hub has almost all the same ports as the Control Hub but doesn't have any wireless capability. Every robot must use the Control Hub to pair with the driver station, but not all robots will need to use an Expansion Hub.



4.	Select "New" in the top left hand corner.	Active Configuration: miniBot New Available configurations: MiniBot Edit Activate Delete
5.	Select "Expansion Hub Portal 1"	Active Configuration: (unsaved) <no config="" set=""> Save Cancel Scan Press the Save button to persistently save the current configuration Press the Scan button to rescan for attached devices USB Devices in configuration: Image: Cancel of the set o</no>
6.	Now you have 2 Hubs to choose from. Configure and program as necessary. Please see the "Configure your robot" section of this document for an overview of configuration.	Active Configuration: (unsaved) <no config="" set=""> Done Cancel Expansion Hub Portal 1 </no>

2.5 SWITCHING WIFI CHANNELS

The Control Hub can utilize either the 2.4 GHz or 5 GHz WiFi band. By default the Control Hub is set to a channel on the 2.4 GHz band. REV Robotics advises that during competition teams utilize a 5 GHz channel for robot communication. Consulting with the FTA/CSA at a tournament for the channel to utilize is advised. The following steps will show how to switch the Control Hub to a 5 GHz channel.





2.6 FACTORY RESET

The Control Hub can reset to factory settings. This will replace the reset the password and SSID name while keeping the Robot Controller application installed on the Control Hub.

Factory Reset Procedure					
1.	Press and hold the button on the front of the Control Hub.				
2.	While pressing the button, power on the Control Hub.				
3. Release button when Control Hub LED flashes PINK. When Control Hub flashes BLUE then GREEN it has completed the reset and is ready to connect.					